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| From: DTEC | ARM20-6.2.11  (DTEC4-15.3.3) |
| To: ARM |  |

LIAISON NOTE

on AtoNs specifically designed to support autonomous navigation

# Inroduction

The DTEC committee welcomes the valuable feedback received from the ARM19 meeting related to the draft new Guideline on Digitalization of Waterways. The DTEC committee will take into account the comments provided while continuing the drafting of the guideline.

Following the proposal from ARM, DTEC committee has drafted a Discussion paper on AtoNs specifically designed to support autonomous navigation.

The Discussion paper and the 20th IALA Conference presentation on the same subject are attached to this liaison note. The conference presentation is the original source of the proposals presented in the Discussion paper.

DTEC committee plans to remove the material related to the AtoNs specifically designed to support autonomous navigation (Section 7.4) from the Draft Guideline and send an updated version to other technical committees for review and comments after its next meeting, DTEC 5.

# Action requested

The ARM committee is requested to

1. note that DTEC has addressed the comments provided by ARM
2. consider the information in the discussion paper in the future work of ARM

Attachments:

* DTEC4- output X Discussion paper on AtoNs specifically designed to support autonomous navigation
* Conference paper (pdf): 'What makes an AtoN “MASS-compatible?” / Oltmann, Jan-Hendrik. 2023. 'What makes an AtoN >MASS-compatible<'. Proceedings of the 20th IALA Conference, Vol 2. Saint-Germain-en-Laye: IALA. 138-154.